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Solution: The key is to draw the Free Body Diagram (FBD) in order to keep the signs right. To identify the direction of the spring forces on the left side object, let $x_2 = 0$ and increase x_1 from 0. Then the k_1 spring on the left will be stretched producing its spring force to the left and the k_2 spring

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a) Design a state feedback controller for the following system so that the closed-loop step response has an overshoot of less than 5% and a 1% settling time under 4.6 sec. b) Use the `stepcommand` in MATLAB to verify that your design meets the specifications. If it does not, modify your feedback gains accordingly.

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1.1. PROBLEMS AND SOLUTIONS. 1005. 4. Many variables in the human body are under feedback control. For each of the following controlled variables, draw a graph showing the process being controlled ...

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