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AS LANGUAGE

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I-2 November 20, 1998

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INTRODUCTION The AS Language Reference Manual is designed to assist the user whose primary responsibility includes programming and operating Kawasaki industrial robots on a daily basis. AS Language is a computer control language designed specifically for use with

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1.2 INSTALLATION
ENVIRONMENTS OF
ROBOT CONTROLLER
Install the controller in
a site that satisfies all
the following
environmental
conditions: 1. Ambient
temperature during
operation: within 0 - 45
C or within 0 - 40 C

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when placing E7x controller vertically and E91 controller 2.

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1.2 Installation
Environments of Robot
Controller Install the
controller in a site that
satisfies all the
following

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environmental

conditions: 1. Ambient temperature during operation: within 0 to 45 C. 2. Relative humidity: 35 to 85%RH (Non condensing) 3.

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NETWORK

CONNECTION WITH

HUB This diagram

shows the Ethernet

network using a hub

for 10BASE-T/100BASE-

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TX connection. In this case, use Ethernet straight cable for connection. PC Controller Transceiver Hub To other robot controller, etc. Connect if

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and other relevant
manuals such as the
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arc weld robot
controlled via E series
controller. Once the
contents of these
manuals are
thoroughly read and
understood the robot
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Servo-Drive Heavy-
Duty Industrial Robot
UX100/120/150 KEY
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standard (7 optional)

Robot Arm Type:

Articulated Payload:

70~ 300 kg (154 - 660
lbs)

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Appendix 3

Deformation of
Welding Torch and
Replacement Kawasaki
Robot Installation and
Connection Manual -
Arc Welding

Application - Appendix
3 Deformation of
Welding Torch and
Replacement During
welding by the robot,
the welding torch may
interfere with the
workpiece due to an
unexpected trouble,
and this may result in

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a compact design.

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A001 ROBOT
CONTROLLER
APPLIED MATERIALS**

...

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CONFIGURATION OF
THIS MANUAL This
manual describes the
fundamental
operational procedures
for the Kawasaki C
Series Controller,
Explosion-Proof Type.
Overview and basic
operations that need to

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using Kawasaki Robot
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