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Nonlinear Control Lecture 1: Introduction

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Many people have contributed to this material in nonlinear control. Originally, it was developed by Bo Bernhardsson, Karl Henrik Johansson, and Mikael Johansson. Later contributions have been added by Henning Schmidt,

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Professor Jean-Jacques
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Professor of Brain and Cognitive Sciences, and Director of ... (1986), and “Applied Nonlinear Control” (Slotine and Li, Prentice-Hall, 1991) and is one of the most cited researcher in both systems science and robotics. He was a member of the French

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